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# **Partial Automation for Truck Platooning**

**FHWA Exploratory Advanced Research Project**

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**California PATH Program**

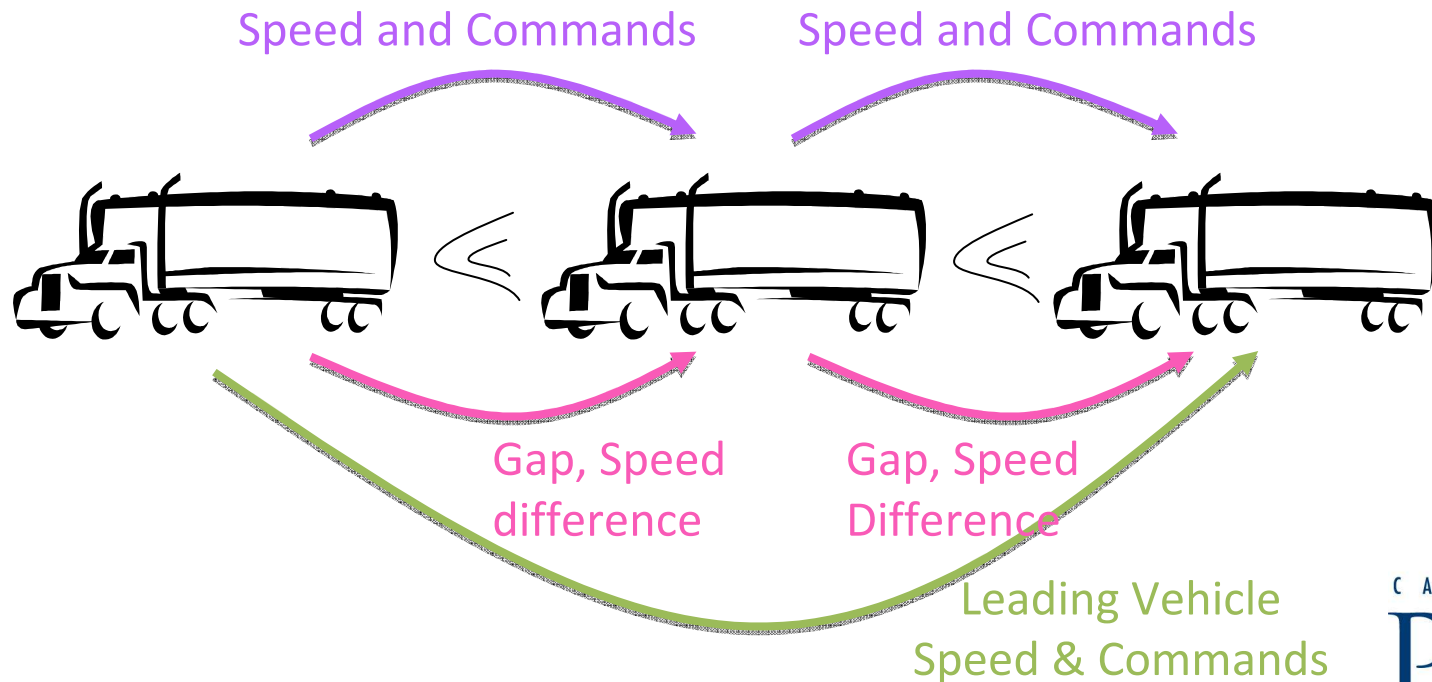
**University of California, Berkeley**

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# Cooperative Adaptive Cruise Control (CACC) for Class-8 Trucks

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- Start with commercially-available Volvo truck adaptive cruise control
- Add vehicle-vehicle (V2V) data communications to enhance performance
- Driver chooses following gap and controls steering



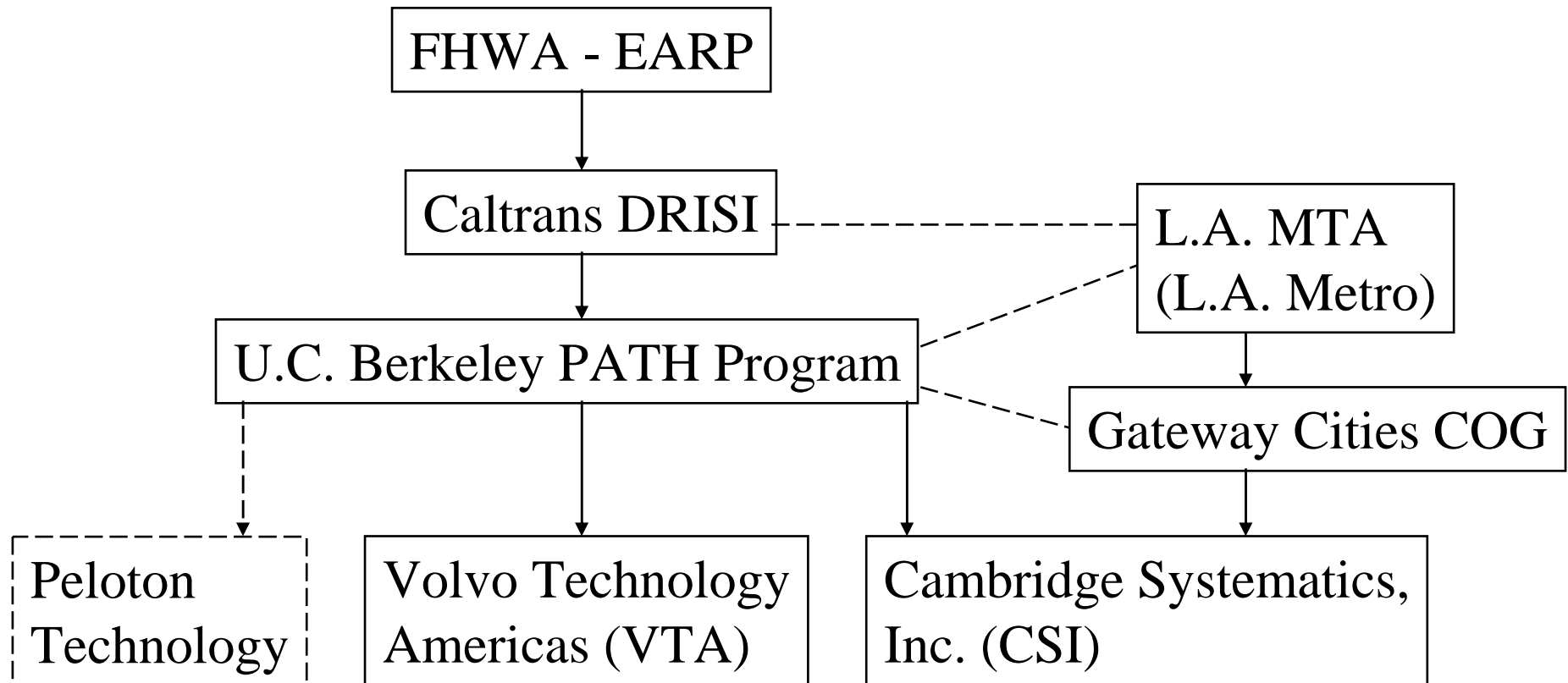
# Project Goals/Objectives

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- **Research questions:**
  - Performance achievable with truck CACC in mixed traffic?
  - Driver preferences for CACC time gaps?
  - Energy savings at preferred time gaps?
  - Benefits in truck lane capacity, energy and emissions?
- **Public policy:**
  - Deployment strategies for truck CACC
  - Synergy with I-710 truck lane development
  - Attractiveness to public and officials

# Project Team

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# Relevant PATH Experience

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- **Development and testing of truck automation systems on closed test sites since 1998**
  - **Wind-tunnel tests of drag reductions on scale model trucks at USC since 1995 – potential saving up to 25% by follower**
- **Two-truck platoon development and testing 2000-2003 for Caltrans (constant-spacing gaps 3 – 10 m)**
  - **Leader saved 10%, follower saved 12% fuel**
- **Three-truck platoon development and testing for FHWA, 2007-2011 (constant-spacing gaps 4 - 10 m)**
  - **Leader saved 4%, followers saved 10-14% fuel**
  - **At sea level and highway cruising speeds, could have saved 1.5X more**
- **CACC simulated, implemented and tested on cars and crossovers**



# System Description

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- **Cooperative ACC with constant time-gap vehicle following (not a close-coupled platoon)**
  - **For passenger cars, shortest gap was 0.6 s (58 ft gap at 65 mph)**
- **Based on production ACC system on Volvo trucks + Denso WSU DSRC radios**
- **DSRC provides enhanced and earlier information about motions of and commands issued to preceding trucks**
- **Three Class-8 tractors to be equipped and tested**

# Project Experimental Work Planned

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- **Develop truck CACC, starting from existing Volvo ACC (2014-15)**
  - **Tighter control of gaps**
  - **Option to choose shorter gaps**
  - **Driver interface based on simulator tests**
- **Test driver preferences for gap settings (2015)**
  - **Formal human factors experiment, with representative truck drivers**
- **Measure energy savings at preferred gaps (2016)**
- **Public demonstration in southern California (2016)**